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## Topics are welcome to contribute:

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- Autonomous mobile robots;
- Unmanned aerial vehicles;
- Autonomous mobile manipulators;
- Autonomous underwater vehicles;
- Autonomous humanoid robot;
- Robust control of robot-like mobile machines (construction, etc.);
- Robust control of complex robot-like production machines and plants;
- Autonomous navigation and obstacle avoidance;
- Path planning and trajectory tracking;
- Robotic manipulators;
- Decentralized robotic and robot-like control systems;
- Swarm robotic systems;
- Heterogeneous robotic systems;
- Human-robot cooperation;
- Human-robot interaction;
- Computer vision systems in assisting industrial robotics systems;
- Sensor fusion technologies for unmanned vehicles and intelligent robotic systems;
- Practical applications of unmanned vehicles and intelligent robotic systems.

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